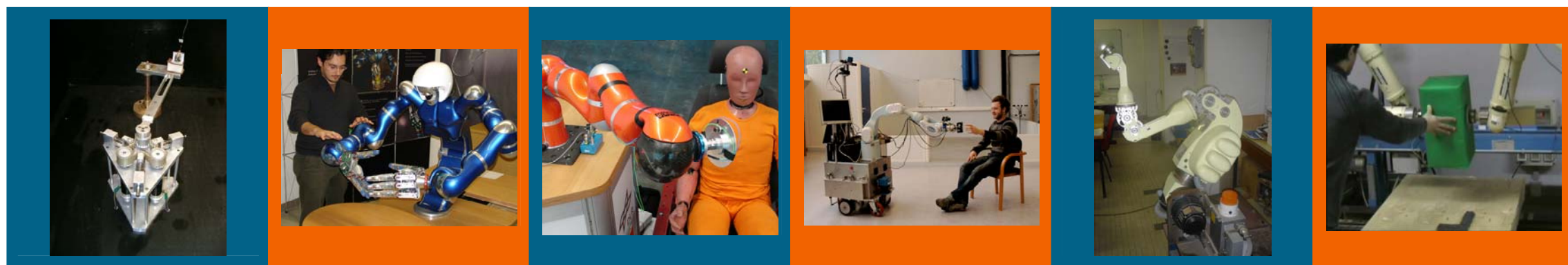




# Physical Human-Robot Interaction: DepENDability and Safety

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This project aims at developing robots that can co-exist and co-operate with people, enabling a physical human-robot interaction which is dependable and safe: in a word, to make robots and humans **PHRIENDS**

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